A detection method for logic functions suitable for dual-logic synthesis

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Abstract

Logic functions can be implemented in either AND/OR/NOT-based traditional Boolean (TB) logic or AND/XOR-based Reed–Muller (RM) logic. To the majority of logic functions, it will be beneficial to be partially implemented in both TB logic and RM logic, called dual-logic. In this paper, a detection condition favoring dual-logic synthesis is proposed. A corresponding detection algorithm is developed and implemented in C. The algorithm is applied to test a set of MCNC91 benchmarks for verifying the algorithm. The results show that the proposed algorithm is more efficient than published ones.

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1. Introduction

Logic functions can be implemented by either using AND/OR/NOT-based traditional Boolean (TB) logic or using AND/XOR-based Reed–Muller (RM) logic. Statistically, 50% of applications can obtain better design under RM logic domain than that under TB logic domain [1,2]. For example, for an \( n \) variable parity function, using TB logic to implement takes \( 2^{n-1} \) product terms or \( 2^{n-1}n \) literals because each product term contains \( n \) literals. However, if RM logic is used to implement, it only takes \( n \) product terms or \( n \) literals because each product term consists of only one literal [3–6]. Furthermore, with the increase in \( n \), potential savings of a chip area and power dissipation are significant. In addition, RM logic-based design is of good testability, which offers an efficient solution to overcome verification difficulty for today’s IC industry. Therefore, for digital designs, both TB logic and RM logic are of equal importance. If two logic domains are combined to synthesize logic functions, then better solutions could be obtained. To do so, the first task is to efficiently detect whether a logic function is favorable to implement under TB logic or RM logic. A traditional synthesis flow is as follows: converting a logic function in both TB logic and RM forms; synthesizing them under two logic domains, respectively; comparing the synthesis results and determining implementation of the logic domain. However, there are two drawbacks for this flow. First, it is time-consuming. Second, only a small percentage of logic functions are favorable to implement under TB logic or RM logic. In fact, the majority of logic functions are favorable to partial implementation in both TB logic and RM logic, which is called dual-logic synthesis.

In terms of dual-logic synthesis, to our best knowledge, the only work was done by Dubrova and Bengtsson [7], which is an XOR logic detection algorithm. The authors proposed a sufficient condition. If a function meets the sufficient condition, then the function can be represented in a form as \( f = (g \oplus h) + r \) and the number of product terms is fewer than that in the Sum of Products (SOP) form. However, the condition is based on counting the number of minimum product terms in the TB logic form compared...
with the number of non-minimum product terms in $f = (g \oplus h) + r$. Furthermore, the condition does not take the structure of the remainder function $r$ into account. Thus, the application of the condition has its limitations. Take the function in Fig. 1, for example, the function meets the sufficient condition proposed in [7], which means the function synthesizing in Karnaugh loops as in Fig. 1(a) can obtain better results than that in Fig. 1(b). However, from Fig. 1(a), it takes four product terms while from Fig. 1(b) it only takes three product terms.

In this paper, a detection condition favoring dual-logic domain synthesis is proposed. A corresponding detection algorithm is developed and implemented in C. The algorithm is applied to a set of MCNC91 benchmarks to test the algorithm efficiency.

2. Terminology and definitions

If the function $f: \{0, 1\}^n \rightarrow \{0, 1\}$, then it is called a completely specified function, or CSF in brief. If function $f: \{0, 1\}^n \rightarrow \{0, 1, -\}$, where “-” denotes a “do not care value”, then it is called an incompletely specified function, or ISF in brief. For an ISF, $F_p$, $R_p$ and $D_p$ are used to denote onset, offset and do not care set of the function $f$, respectively; while for a CSF, only $F_p$ and $R_p$ exist. In this paper, CSF is focused. For convenience, the following definitions are helpful.

**Definition 1.** One decimal integer $i$ is represented into $n$-bit binary code $(x_{n-1}x_{n-2}\ldots x_0)$, $i = \sum_{k=0}^{n-1} a_k \cdot 2^k$, and $x_k \in \{0, 1\}$; $H_{ij} = \sum_{k=0}^{n-1} (x_k \oplus y_k)$ is called the Hamming Distance (HD) of two binary codes, $(x_{n-1}x_{n-2}\ldots x_0)$, $(y_{n-1}y_{n-2}\ldots y_0)$, corresponding to two decimal numbers $i$ and $j$ where $i = \sum_{k=0}^{n-1} x_k \cdot 2^k$, $j = \sum_{k=0}^{n-1} y_k \cdot 2^k$, and “$\oplus$” represents exclusive OR.

Given an $n$ variable function $f(x_0,x_1,\ldots,x_{n-1})$, it can be represented as $f(x_0,x_1,\ldots,x_{n-1}) = \sum_{i=0}^{2^n-1} a_i m_i$ where $m_i$ is called minterm, which is a Boolean product of the variables, $x_0, x_1, \ldots, x_{n-1}$, or their complements, and the variables in $m_i$ are also called literals. $a_i \in \{0, 1\}$ is the coefficient of the $i$th minterm. If $a_i = 1$, the $i$th minterm exists in the function expression. Otherwise, it does not. $\{a_i = 1\}$ consists of the onset $F_i$. A product term is also called a cube. Hence, cube and product term are used interchangeably in this paper.

**Definition 2.** The intersection of two sets $A$ and $B$, denoted by $A \cap B$, is the union of the pairwise intersection of the cubes from sets $A$ and $B$. The union of the two sets, denoted by $A \cup B$, is the union of the cubes from $A$ and $B$.

**Definition 3.** The complement of the $A$ is denoted by $\overline{A}$ and $A \cap \overline{A} = \phi$.

**Definition 4.** A cube is called the minimum cube if it does not cover any other cubes except itself. A supercube of two cubes $a$ and $b$ is the cube at least covering $a$ and $b$, denoted by $sup(a, b)$.

From the above definitions, it is known that any minterm $m_i$ covers one Karnaugh lattice while any supercube covers at least two Karnaugh lattices. It can be deduced that a supercube of two minimum cubes $m_i$ and $m_j$ with $H_{ij} = 2$ covers four Karnaugh lattices.

**Definition 5.** Let $l_1, l_2, \ldots, l_k (k > 1)$ be cubes from the onset $F_f$ of the Boolean function $f: \{0, 1\}^n \rightarrow \{0, 1\}$ and let the intersection of $sup(l_1, l_2, \ldots, l_k)$ with the offset $R_f$ be a non-empty set of cubes $sup(l_1, l_2, \ldots, l_k) \cap R_f = \bigcup_{i=1}^{p} {c_i}$, $p \geq 1$. $sup(l_1, l_2, \ldots, l_k)$ is called the $\frac{1}{p}$-cube.

For example, Fig. 2 is a Karnaugh map of a four variable function $f = \sum(m_0, m_5, m_{11}, m_{14}, m_{15})$. The Karnaugh loop a is a $\frac{1}{4}$-cube while the Karnaugh loop b is a $\frac{1}{2}$-cube.

3. Principle of sufficient condition

A logic function can be implemented by AND/OR/NOT-based TB logic, denoted as $f_B$, or by AND/XOR-based RM logic, denoted as $f_{RM}$. For a specific logic function, in terms of die size and power dissipation, it is interesting to know which logic is favorable to implement; it is more important to know whether the logic function is beneficial for mono-logic or dual-logic being implemented. This problem can be addressed as follows.

Given a logic function in TB logic form, detect whether a compact form, in which part of the function is implemented by RM logic and the remainder is implemented by TB logic, could be obtained under dual-logic synthesis. In other words, an AND/OR/NOT-based expression $f_B$ can be transformed into $f_B^{+} + f_{RM}$ called dual-logic, denoted as $f_f^{+} = f_B^{+} + f_{RM}$. Here, $f_{RM}$ denotes that the func-
tion is expressed into RM form while $f^*_F$ represents that the function is in Boolean form; while $f_B$ and $f_D$ have the same logic function.

To see whether dual-logic synthesis is beneficial to the function $f_B$, a cost function is needed. As known, in two-level AND/OR expression, the number of cubes is used to evaluate the implementation cost of the function while in multi-level expression the number of literals is used as the cost. Here, both the number of cubes and the number of literals are used to measure the cost. The criteria to tell in multi-level expression the number of literals is used as the cost; for level AND/OR expression, the number of cubes is used.

Lemma 1 gives a condition for substituting a subset $F_S$ of the onset $F_F$ of a function $f_B$ by two functions $f^*_F$ and $f_{RM}$ so that $f_B = f^*_F + f_{RM}$ and the implementation cost in $f^*_F + f_{RM}$ is smaller than that in $f_B$. The following theorem guarantees that this condition is sufficient.

**Theorem 1 (Sufficient condition).** If a Boolean function $f_B$ satisfies Lemma 1 for some set of cubes $(l_1, l_2, \ldots, l_k)$, $i \in F_F$, $\forall i \in \{1, 2, \ldots, k\}$, then the implementation cost of $f_D$ is smaller than that of $f_B$.

**Proof.** Suppose that a part of the function $f_B$ satisfies Case (i) in Lemma 1. Then Eq. (1) is satisfied. From the right part of Eq. (1), $\bigcup_{i=1}^p l_i \cup \bigcup_{i=1}^p (sup(b_i, c_i) - c_i)$, which is an AND/OR/NOT-based expression, it costs $p + k$ terms. However, from the left part of Eq. (1), $sup(l_1, l_2, \ldots, l_k) \cap R_F = \bigcup_{i=1}^p c_i$, $p \geq 1$, $k = 1, 2, \ldots, 2^n$.

(i) if $p < k$, $k = 2, 3, \ldots, 2^n - 1$, for each cube $c_i$, a cube $b_i \in F_F$ such that $sup(b_i, c_i) \cap R_F = c_i$ can be found as well as $sup(l_1, l_2, \ldots, l_k) \cap sup(b_i, c_i) = c_i$, then

$$sup(l_1, l_2, \ldots, l_k) \cap \bigcup_{i=1}^p sup(b_i, c_i)$$

$$= \bigcup_{i=1}^p sup(b_i, c_i) - \bigcup_{i=1}^p sup(b_i, c_i)$$

$$= \bigcup_{i=1}^p (sup(b_i, c_i) - c_i)$$

$$sup(l_1, l_2, \ldots, l_k)$$ is called the $k_{1^p}$-cube.

(ii) if $p = k$, $k = 2^r$, and $r = 1, 2, 3, \ldots, n - 1$, for each cube $l_i$, always there is cube $l_j$, and $l_i, l_j \in F_F$, $i \neq j$, such that $sup(l_i, c_i) \cap R_F = sup(l_j, c_j) \cap R_F = c_i$ can be found as well as $sup(l_i, c_i) \cap sup(l_j, c_j) = c_i$. The minimum HD between any two cubes is 2. Then

$$sup(l_1, l_2, \ldots, l_k) \cap \bigcup_{j=1}^k \bigcup_{h=1}^k sup(l_j, c_j) \cap \bigcup_{h=1}^k l_h$$

$$= \bigcup_{h=1}^k l_h$$

$$sup(l_1, l_2, \ldots, l_k)$$ is called the $1_{1^p}$-cube.

Therefore, under the dual-logic synthesis, $f_D = f^*_F + f_{RM}$ and the implementation cost in $f^*_F + f_{RM}$ is smaller than that in $f_B$.

In the following, two examples are shown to explain how to apply Theorem 1 to detect functions.

**Example 1.** A 4-variable function $f_1$ is shown in Fig. 3.

On the one hand, let $m_1 = 0001$, $m_2 = 0101$, $m_3 = 1001$, and $m_4 = 1100$. Then we have $sup(m_1, m_2, m_3) = 1101$ as the loop in Fig. 3 and $sup(m_1, m_2, m_3) \cap R_F = 1101 = c_1$. Since $p = 1$ and $k = 3$, $sup(m_1, m_2, m_3) = \frac{3}{2}$-cube. It can be seen that $b_1 = m_4 = 1100$ satisfies $sup(b_1, c_1) \cap R_F = c_1$. Since $sup(b_1, c_1) - c_1 = b_1$, we obtain that $sup(m_1, m_2, m_3) \cup sup(b_1, c_1) = m_1 \cup m_2 \cup m_3 \cup b_1$.

Hence, $f_{RM} = x_1x_2 \oplus \overline{x_1}x_3x_4$. On the other hand, let $m_5 = 0110$ and $m_6 = 1110$. Then we have $f^*_F = x_1x_2x_4$. Hence, under the dual-logic synthesis, $f_D = f_{RM} + f^*_F = x_1x_2 \oplus \overline{x_1}x_3x_4 + x_1x_2x_4$. However, if Boolean logic is used to synthesize the function, then $f_1 = f_B = x_1x_2x_7 + \overline{x_1}x_3x_4 + x_1x_2x_4 + x_1x_3x_4$. It can be seen that using RM logic can save one cube in terms of the number of cubes.
4 literals in terms of the number of literals. The function meets Case (i) in Lemma 1.

Example 2. A 4-variable function $f_2$ is shown in Fig. 4.

Let $m_1 = 0001$, $m_2 = 0100$, $m_3 = 1101$ and $m_4 = 1000$. Then we have \( \sup(m_1, m_2, m_3, m_4) = \emptyset \). The output is the onset, but not to optimize the function. The proposed synthesis. Exhaustively searching such a subset may not be necessary since what we need is to quickly evaluate whether a function is likely to benefit from dual-logic implementation, but not to optimize the function. The proposed algorithm is used to lead to the solution. The input is the onset $F_f$ and offset of $R_f$. The output is “YES” if a function is likely to benefit from dual-logic minimization, “NO” otherwise. The algorithm repeats the following steps:

Step 1. Choose a pair of cubes, $m_j, m_{j+1}$, and compute its supercube $\sup(m_j, m_{j+1})$.
Step 2. Compute the intersection $\sup(m_j, m_{j+1}) \cap R_f = \bigcup_{i=1}^p c_i$.
Step 3. Check whether $\sup(m_j, m_{j+1})$ is a kind of $\frac{1}{2}$-cube. If yes, let $N_{RM1} = N_{RM1} + 1$, and delete $m_j, m_{j+1}$ and go to Step 1. If no, go to Step 4.

4. Dual-logic detection algorithm

Based on Theorem 1, one is able to detect whether a logic function is beneficial for using dual-logic implementation. The larger the subset of the onset of a function $f$ satisfying Lemma 1, the more the $f$ can benefit from dual-logic synthesis. Exhaustively searching such a subset may not be necessary since what we need is to quickly evaluate whether a given function is likely to benefit from dual-logic implementation, but not to optimize the function. The proposed algorithm is shown as follows:

Check_Dual_Lo\(gic(F_f, R_f)\)

Input: $F_f, R_f$

Output: “YES” if function is likely to benefit from dual-logic minimization, “NO” otherwise.

\[ N_{RM1} = 0, N_{RM2} = 0; \]

\[ \text{for (each pair of cubes, } (m_j, m_{j+1}) \in (F_f \times F_f)\}; \]

\[ \text{flag_lemma_ satisfied} = 0; \]

\[ \text{Compute_supercube} \sup(m_j, m_{j+1}); \]

\[ \text{for (each cube } c_i \in \{c_1, \ldots, c_p\} \}
\]

\[ \text{flag found a} = 0; \]

\[ \text{for (each cube } b_i \in F_f \}
\]

\[ \text{Compute supercube} \sup(b_i, c_i); \]

\[ \text{if}(\sup(b_i, c_i) \cap R_f = c_i)\}

\[ \text{flag found a} = 1; \]

\[ N_{RM1} = N_{RM1} + 1; \]

\[ \text{break}; \]

\[ \text{return (YES); } N_{RM1}, N_{RM2}; \]

\[ \text{else} \]

\[ \text{return (NO); } \]

The main purpose of the proposed algorithm is to determine whether the expression of a function is more compact using dual-logic synthesis than using Boolean logic by

Fig. 4. Part of function $f_2$ that meets case (ii) in Lemma 1.
5. Experimental results

The proposed algorithm was implemented in C and run under Pentium 486/2.4 GHz/512 M. A set of experiments was performed on 18 benchmarks from MCNC91. Table 1 summarizes the results. Column 1 shows the circuit name. Column 2 gives the number of inputs n and outputs. Column 3 refers to the cube number of F_i in the cover computed by Espresso [5]. Column 4 gives the number, N_{RM1}, satisfying Lemma 1(i) while Column 5 shows the number, N_{RM2}, satisfying Lemma 1(ii). Column 6 gives the number, N_{RM}, that shows the satisfaction of Lemma 1. Column 7 shows the result “Yes” or “No” to indicate whether the function is suitable to the dual-logic synthesis. The final column presents the CPU time to detect the function.

From Theorem 1, the larger the function with N_{RM}, the less the cost to implement under the dual-logic synthesis. From the table, it can be seen that 16 out of 18 circuits are marked with “Yes”, which indicates that those functions are beneficial from the dual-logic synthesis since they have larger N_{RM}. Functions with large N_{RM}, like 9sym, Newill, Rd84, Sym10, XOR5, T481, Cordic are known to have a smaller cost using dual-logic than using Boolean logic, which is confirmed by the published results [7–9]. However, functions like Ryy6, Cm150a are not beneficial under dual-logic synthesis. It should be pointed out that the algorithm in [7] is unable to detect T481 properly. But the detection result based on the proposed algorithm shows that it is beneficial for T481 to synthesize under dual-logic that is confirmed in [7] based on its structure analysis. From the CPU time in the table, it is known that the proposed algorithm has reasonable time complexity.

6. Conclusions

In this paper a sufficient condition is formulated for a function f(x_0, x_1, …, x_n−1) to be synthesized under dual-logic domain with less cost than that based on Boolean logic. Based on this condition, an algorithm for detecting whether a function is likely to benefit from dual-logic synthesis is developed and implemented in C. The experimental results tested on MCNC91 benchmarks confirm that the proposed algorithm can properly detect whether the functions are beneficial under the dual-logic domain synthesis. Future work will cover how to optimize a function under the dual-logic synthesis.

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